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## HARMONIC MAPPINGS ONTO $R$-CONVEX DOMAINS


#### Abstract

The plane domain $D$ is called $R$-convex if $D$ contains each compact set bounded by two shortest sub-arcs of the radius $R$ with endpoints $w_{1}, w_{2} \in D,\left|w_{1}-w_{2}\right| \leqslant 2 R$. In this paper, we prove the conditions of $R$-convexity for images of disks under harmonic sense preserving functions. The coefficient bounds for harmonic mappings of the unit disk onto $R$-convex domains are obtained.


Key words: harmonic mappings, $R$-convex domains, coefficient bounds

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1. Preliminaries. For a given pair of points $w_{1}, w_{2} \in \mathbb{C}$ such that $\left|w_{1}-w_{2}\right| \leqslant 2 R$ with $0<R<\infty$ we define the $R$-convex hull $E_{R}\left(w_{1}, w_{2}\right)$ of $w_{1}, w_{2}$ as a compact set bounded by the two shortest arcs of the circles of radius $R$ with endpoints $w_{1}, w_{2}$. The set $E_{R}\left(w_{1}, w_{2}\right)$ is strictly convex for each $R>0$ and tends to the segment $\left[w_{1}, w_{2}\right]$ when $R \rightarrow \infty$.
Definition 1. The set $A \subset \mathbb{C}$ is called $R$-convex if $A$ contains each set $E_{R}\left(w_{1}, w_{2}\right)$ provided that $w_{1}, w_{2} \in A$ and $\left|w_{1}-w_{2}\right| \leqslant 2 R$.

It is clear that the Jordan domain $D \subset \mathbb{C}$ is $R$-convex if and only if its closure $\bar{D}$ is $R$-convex. Of course, $R$-convex domains are strictly convex.
$R$-convex sets $\in \mathbb{R}^{n}$ were introduced and studied in [13, 14]. $R$-convex sets and domains play an important role in convex analysis and so have applications in many branches of mathematics, physics and economic sciences.
A.W. Goodman [8] defined the convex functions of bounded type independently in the geometrical function theory as an univalent analytic function $h$ in the unit disk $\mathbb{D}=\{z \in \mathbb{C}:|z|<1\}$, such that $\liminf _{|z| \rightarrow 1} k_{h}(z) \geqslant$ $1 / R>0$. Here $k_{h}(z)=\operatorname{Re}\left\{z h^{\prime \prime}(z) / h^{\prime}(z)+1\right\} /\left|z h^{\prime}(z)\right|$ is the curvature of © Petrozavodsk State University, 2019
the image $\Gamma_{r}=h\left(\gamma_{r}\right)$ of the circle $\gamma_{r}=\{z \in \mathbb{D}:|z|=r\}$ under the mapping $h$ at the point $h(z)$. The curvature $k_{h}$ is defined by a standard way as $k_{h}=d \theta / d s$, where $s$ is the natural parameter on $\Gamma_{r}$ and $\theta$ is the argument of the tangent vector to $\Gamma_{r}$.

Let $R \in(0,+\infty)$ be given and $C_{R}$ denote a family of convex analytic functions $h$ in $\mathbb{D}$ of bounded type, such that $h(0)=h^{\prime}(0)-1=0$. These classes were studied by A.W. Goodman $[8,10]$ and K.-J. Wirths [19]. In particular, growth, covering and distortion theorems in $C_{R}$ were proved, as well as coefficient bounds.

Interrelation between $R$-convex domains and analytic univalent functions onto such domains was revealed and investigated in the paper [18] by V. Starkov and N. Shmelev. They proved that for locally univalent analytic function $h$ in $\mathbb{D}$ the domain $D=h(\mathbb{D})$ is $R$-convex if and only if

$$
\begin{equation*}
\operatorname{Re}\left\{z \frac{h^{\prime \prime}(z)}{h^{\prime}(z)}+1\right\} \geqslant \frac{\left|z h^{\prime}(z)\right|}{R} \text { for all } z \in \mathbb{D} \tag{1}
\end{equation*}
$$

More than that, (1) is equivalent to the statement that domains $D_{r}=h\left(\mathbb{D}_{r}\right)$ are $R$-convex for all $r \in(0,1]$, where $\mathbb{D}_{r}=\{z \in \mathbb{D}:|z|<r\}$. So, the heredity property is valid for $R$-convexity of $h\left(\mathbb{D}_{r}\right)$ in the case of analytic functions. Functions $h$ that satisfy condition (1) are univalent.

The theorem of Peschl (cf., $[12,19]$ ) claims that if $h \in C_{R}, R>0$, then $k_{h}(z)$ has not local minimums in $\mathbb{D} \backslash\{0\}$ and $k_{h}(z)>1 / R$ in $\mathbb{D} \backslash\{0\}$. Therefore, $h$ is an analytic convex function of bounded type if and only if (1) is true in $\mathbb{D}$ for some $R>0$. This result, together with criterion (1) of $R$-convexity due by V. Starkov and N. Shmelev, immediately leads to

Proposition 1. $C_{R}$ consists of univalent analytic functions $h$ in $\mathbb{D}$ such that $h(0)=h^{\prime}(0)-1=0$ and $h(\mathbb{D})$ is $R$-convex domain.

In this paper, we obtain the conditions of $R$-convexity of $f(\mathbb{D})$ for sensepreserving harmonic functions and prove some estimations and coefficient bounds for the class of normalised univalent harmonic mappings of the disk $\mathbb{D}$ onto $R$-convex domains.

Consider a harmonic and sense-preserving function $f$ in $\mathbb{D}$. It is wellknown (cf., [5]) that every such function $f$ has a form $f=h+\bar{g}$, where $h, g$ are analytic in $\mathbb{D}$ and

$$
\begin{equation*}
h(z)=\sum_{k=0}^{\infty} a_{k} z^{k}, \quad g(z)=\sum_{k=1}^{\infty} b_{k} z^{k} \tag{2}
\end{equation*}
$$

The dilatation $\omega(z)=g^{\prime}(z) / h^{\prime}(z)$ of sense-preserving harmonic function $f$ is analytic in $\mathbb{D}$ and $|\omega(z)|<1$ for all $z \in \mathbb{D}$. The tangent vector $\tau(t)$ to curve $\Gamma_{r}=f\left(\gamma_{r}\right), r \in(0,1)$, at the point $f(z), z=r e^{i t}$, has a form

$$
\tau(t)=i\left(z h^{\prime}(z)-\overline{z g^{\prime}(z)}\right) \text { and } \arg \tau(t)=\frac{\pi}{2}+\operatorname{Im} \ln \left(z h^{\prime}(z)-\overline{z g^{\prime}(z)}\right)
$$

So, direct calculations show that the curvature $k_{f}(z)=(\arg \tau(t))^{\prime} /|\tau(t)|$ of $\Gamma_{r}$ can be computed as

$$
\begin{equation*}
k_{f}(z)=\frac{1}{\left|z h^{\prime}(z)-\overline{z g^{\prime}(z)}\right|} \operatorname{Re}\left\{\frac{z^{2} h^{\prime \prime}(z)+\overline{z^{2} g^{\prime \prime}(z)}+2 \overline{z g^{\prime}(z)}}{z h^{\prime}(z)-\overline{z g^{\prime}(z)}}+1\right\} . \tag{3}
\end{equation*}
$$

It is clear that harmonic sense-preserving function $f$ should be univalent in $\mathbb{D}_{r}$ if $k_{f}(z) \geqslant 0$ for all $z \in \gamma_{r}$ and domains $D_{r}=f\left(\mathbb{D}_{r}\right)$ will be convex in this case. This is a corollary of the argument principle [5]. It is natural to ask what conditions for the function $f$ guarantee $R$-convexity of $D_{r}$ for $r \in(0,1]$.
2. Conditions of R-convexity. It is well-known (cf., $[3,5]$ ) that harmonic functions $f=h+\bar{g}$ do not possess the heredity property in the case of convexity of $f(\mathbb{D})$. If domain $f(\mathbb{D})$ is convex for a harmonic univalent function $f$ then $f\left(\mathbb{D}_{r}\right)$ can be not convex for all $r \in\left(r_{0}(f), 1\right)$. So we can't expect the $R$-convexity of $f\left(\mathbb{D}_{r}\right)$ when $f(\mathbb{D})$ is $R$-convex and function $f$ is harmonic. The next result describes the $R$-convexity of $f\left(\mathbb{D}_{r}\right)$ in terms of curvature of its boundary.

Theorem 1. Let $f=h+\bar{g}$ be a sense-preserving harmonic mapping of the unit disk $\mathbb{D}$ and $r \in(0,1)$. The domain $D_{r}=f\left(\mathbb{D}_{r}\right)$ is $R$-convex if and only if

$$
\operatorname{Re} \frac{z^{2} h^{\prime \prime}(z)+\overline{z^{2} g^{\prime \prime}(z)}+z h^{\prime}(z)+\overline{z g^{\prime}(z)}}{z h^{\prime}(z)-\overline{z g^{\prime}(z)}} \geqslant \frac{\left|z h^{\prime}(z)-\overline{z g^{\prime}(z)}\right|}{R}
$$

for all $z$ such that $|z|=r$.
Proof. To prove this criterion it is sufficient to note that the arbitrary infinitely-smooth Jordan domain is $R$-convex if and only if the curvature of its boundary is not less than $1 / R$ at every point. This fact was proved in [18] by V. Starkov and N. Shmelev in the course of deriving of the main results.

In our case, if function $f$ is sense-preserving harmonic in $\mathbb{D}$, then the curve $\partial f\left(\mathbb{D}_{r}\right)$ is infinitely smooth for any $r \in(0,1)$ and $k_{f}$ is defined on $|z|=r$. The condition of the Theorem 1 allows us to state that, if domain $D_{r}=f\left(\mathbb{D}_{r}\right)$ is $R$-convex, then $k_{f}(z) \geqslant 1 / R$ for all $z,|z|=r$. And vice versa, if $k_{f}(z) \geqslant 1 / R$ for $|z|=r$, then $k_{f}$ is positive, so $f$ is univalent convex in $\mathbb{D}_{r}$ and $D_{r}$ is Jordan and $R$-convex. Then formula (3) provides us desired criterion of $R$-convexity of $D_{r}$.

The natural question is to describe $R$-convexity of an open domain $D=f(\mathbb{D})$ in terms of harmonic mappings onto this domain. The sufficient condition of $R$-convexity is given by

Theorem 2. Let $f=h+\bar{g}$ be a sense-preserving harmonic mapping of the unit disk $\mathbb{D}$. The domain $D=f(\mathbb{D})$ is $R$-convex if

$$
\begin{equation*}
\liminf _{|z| \rightarrow 1} k_{f}(z) \geqslant \frac{1}{R} \tag{4}
\end{equation*}
$$

where $k_{f}$ is given by (3).
Proof. It was proved in [18] that if domain $D$ is $\tilde{R}$-convex for any $\tilde{R}>R$, then $D$ is $R$-convex. Let a harmonic function $f$ be sense-preserving in the unit disk $\mathbb{D}$ and satisfy condition (4) for some $R>0$, but domain $D=f(\mathbb{D})$ be not $R$-convex. Then there exists $\varepsilon>0$ such that $D$ is not $R_{\varepsilon}$-convex, where $R_{\varepsilon}=R+\varepsilon$. Hence, there exists a pair of points $w_{1}, w_{2} \in D$ such that $\left|w_{1}-w_{2}\right| \leqslant 2 R_{\varepsilon}$ and convex hull $E_{R_{\varepsilon}}\left(w_{1}, w_{2}\right) \not \subset D$.

From the other side, condition (4) means that for any $\varepsilon>0$ we can find $r_{\varepsilon} \in(0,1)$ such that $k_{f}(z) \geqslant 1 / R_{\varepsilon}$ on the whole circle $\gamma_{r}=\{z \in \mathbb{D}:|z|=r\}$ for any $r \in\left(r_{\varepsilon}, 1\right)$. So, the curvature of the image $f\left(\gamma_{r}\right)$ of the circle $\gamma_{r}$ is not less than $1 / R_{\varepsilon}$. Theorem 1 implies that $D_{r}=f\left(\mathbb{D}_{r}\right)$ are $R_{\varepsilon}$-convex for all $r \in\left(r_{\varepsilon}, 1\right)$. Hence, the harmonic function $f$ is sense-preserving and convex in all such $\mathbb{D}_{r}$ and, therefore, $f$ is univalent in $\mathbb{D}$. It is clear that $D=\cup_{r \in\left(r_{\varepsilon}, 1\right)} D_{r}$. So, both points $w_{1}, w_{2}$ belong to $D_{r}$ for all sufficiently large $r \in\left(r_{\varepsilon}, 1\right)$. The $R_{\varepsilon}$-convexity of domains $D_{r}$ for such $r$ implies that $E_{R_{\varepsilon}}\left(w_{1}, w_{2}\right) \subset D_{r} \subset D$ in contradiction with assumption $E_{R_{\varepsilon}}\left(w_{1}, w_{2}\right) \not \subset D$. Therefore, domain $D$ is $R$-convex. $\square$

Remark. The converse statement to Theorem 2 is not true. Even for the harmonic sense-preserving automorphisms of the unit disk $\mathbb{D}$ the values $\liminf _{|z| \rightarrow 1} k_{f}(z)$ can be negative.

To illustrate this remark we consider function

$$
\theta(t)=\left\{\begin{array}{l}
2 t, \text { for } t \in(0, \pi) \\
0, \text { for } t \in[-\pi, 0]
\end{array}\right.
$$

This function induces the continuous mapping $w\left(e^{i t}\right)=e^{i \theta(t)}$ of the unit circle onto itself such that $w\left(e^{i t}\right)$ runs once monotonically (but not strictly monotonically) unit circle while $t$ runs from $-\pi$ to $\pi$. It is known from Radó-Knezer-Choquet theorem [5] that the Poisson integral

$$
f_{\theta}(z)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{1-|z|^{2}}{\left|e^{i t}-z\right|^{2}} e^{i \theta(t)} d t
$$

defines univalent harmonic mapping of $\mathbb{D}$ onto itself with boundary function $e^{i \theta(t)}$. The boundary behaviour of $f_{\theta}$ is such that closed lower half of the unit circle corresponds to the single point 1 , while open upper half of the unit circle is mapped onto whole circle without point 1 . The image of polar grid in $\mathbb{D}$ under mapping $f_{\theta}$ is presented on the left part of the Fig. 1. Note that the images $f_{\theta}\left(\gamma_{r}\right)$ of circles $\gamma_{r}$ are not convex for sufficiently large $r<1$. The geometrical picture of $f_{\theta}\left(\gamma_{r}\right)$ in the neighbourhood of the point 1 is presented on the right part of Fig 1.


Figure 1: Image of polar grid in $\mathbb{D}$ under mapping $f_{\theta}$ (left). The local nonconvex structure of the images of polar circles $\gamma_{r}$ in the neighbourhood of the point 1 (right).

Using Wolfram Mathematica, it is possible to calculate the curvature $k_{f_{\theta}}(z)$ of $f_{\theta}\left(\gamma_{r}\right)$ at points $z=r e^{i t}$. Let $z=r$ tend from the origin to 1 .

The image of this radius under $f_{\theta}$ is marked in the left-hand part of Fig. 1 by the bold line. Fig. 2. illustrates the values $k_{f_{\theta}}(r)$ when $r$ tends to 1 . It can be seen from this dependence that curvatures $k_{f_{\theta}}(z)$ become negative if $z$ goes to 1 along some trajectories. So, $\liminf _{|z| \rightarrow 1} k_{f_{\theta}}(z)<0$. But, from the other side, it is clear that the unit disk is an $R$-convex domain with $R=1$.


Figure 2: The curvature $k_{f_{\theta}}(r)$ for $r \rightarrow 1-$.

This counter-example leads us to the important fact that in contrast to the analytic case, the set of harmonic univalent functions of the disk $\mathbb{D}$ onto $R$-convex domains is wider than the family of harmonic sensepreserving functions satisfying condition (4).

The next question is to find a maximal radius $r_{0}(R)$ such that sensepreserving harmonic function maps every disk $\mathbb{D}_{r}$ onto $R$-convex domain for all $r \leqslant r_{0}(R)$. It is known [5] that near the origin every $f=h+\bar{g}$ with $h, g$ of form (2) and $\left|b_{1}\right|<\left|a_{1}\right|$ maps infinitesimal disks $|z|<\varepsilon$ onto interiors of convex curves close to the infinitesimal ellipses $\left\{a_{0}+a_{1} z+\overline{b_{1} z}\right.$ : $|z|=\varepsilon\}$. So, $f\left(\mathbb{D}_{\varepsilon}\right)$ should be $R$-convex for sufficiently small $\varepsilon>0$.

The linear hull $L(f)$ of a sense-preserving harmonic function $f=h+\bar{g}$ in $\mathbb{D}$ with $a_{0}=a_{1}-1=0$ is defined as the linear-invariant family of all harmonic sense-preserving functions

$$
f_{\Phi}(z)=\frac{f \circ \Phi(z)-f \circ \Phi(0)}{\Phi^{\prime}(0) \cdot h^{\prime} \circ \Phi(0)}
$$

where $\Phi(z)=e^{i \alpha}(z-\zeta) /(1-\bar{\zeta} z)$ runs over the family of the conformal automorphisms of $\mathbb{D}$.

The affine hull $A(f)$ of a harmonic function $f$ is defined as the family
of all harmonic sense-preserving functions

$$
f_{\varepsilon}(z)=\frac{f(z)+\varepsilon \overline{f(z)}}{1+\varepsilon b_{1}}
$$

where $\varepsilon$ runs over the disk $\mathbb{D}$.
Let $A L(f):=A(L(f))$ denote the affine and linear hull of $f$. The subfamily $A L^{0}(f) \subset A L(f)$ consists of functions $\tilde{f}$ such that $\tilde{f}_{\bar{z}}(0)=0$. Define $\alpha_{0}=\alpha_{0}(f)=\sup \left|\tilde{f}_{z z}(0)\right| / 2$ and $\beta_{0}=\beta_{0}(f)=\sup \left|\tilde{f}_{z \bar{z}}(0)\right| / 2$, where the suprema are taken over all $\tilde{f} \in A L^{0}(f)$. It is known [3] that $\alpha_{0}$ is finite for all univalent $f$ and $\beta_{0} \leqslant 1 / 2$. The sharp upper bound of $\alpha_{0}$ for an arbitrary univalent harmonic function $f$ is still unknown (though, conjectured) [3]. However, the sharp upper bounds of $\alpha_{0}$ have been obtained for harmonic functions with some special geometric properties (cf., [3,5]). For more results on linear- and affine-invariant families of harmonic functions, see $[6,11,16,17]$.
Theorem 3. Let a sense-preserving harmonic mapping $f=h+\bar{g}$ of the unit disk $\mathbb{D}$ have form (2) and $a_{0}=a_{1}-1=0, \alpha_{0}<\infty$. Then the domain $D_{r}=f\left(\mathbb{D}_{r}\right)$ is $R$-convex for every $r \leqslant r_{0}(R)$, where $r_{0}(R) \in\left(0, \alpha_{0}+\beta_{0}-\sqrt{\left(\alpha_{0}+\beta_{0}\right)^{2}-1}\right)$ is the smallest positive root of the equation

$$
\begin{equation*}
\frac{1-\left|b_{1}\right|}{\left(1+\left|b_{1}\right|\right)^{2}}\left(\frac{1-r}{1+r}\right)^{\alpha_{0}+3 / 2} \frac{r^{2}-2 r\left(\alpha_{0}+\beta_{0}\right)+1}{r}=\frac{1}{R} \tag{5}
\end{equation*}
$$

Proof. Let $f$ satisfy the conditions of Theorem 3. The upper and lower bounds of curvature $k_{f}(z)$ of images $f\left(\gamma_{r}\right)$ of the circle $\gamma_{r}, r \in(0,1)$, in the linear- and affine-invariant families of harmonic sense-preserving in $\mathbb{D}$ functions $f$ were published in [11]. In particular, it was proved that $f$ is convex in the disk $|z|<\alpha_{0}+\beta_{0}-\sqrt{\left(\alpha_{0}+\beta_{0}\right)^{2}-1}$ and

$$
k_{f}(z) \geqslant \frac{1-\left|b_{1}\right|}{\left(1+\left|b_{1}\right|\right)^{2}}\left(\frac{1-r}{1+r}\right)^{\alpha_{0}+3 / 2} \frac{r^{2}-2 r\left(\alpha_{0}+\beta_{0}\right)+1}{r}
$$

for all $z$ such that $|z| \leqslant r \leqslant \alpha_{0}+\beta_{0}-\sqrt{\left(\alpha_{0}+\beta_{0}\right)^{2}-1}$ and $\left|b_{1}\right|=\left|f_{\bar{z}}(0)\right|$. The validity of Theorem 3 and condition (5) follows from this result immediately.

The values $\alpha_{0}$ and $\beta_{0}$ are known to be $3 / 2$ and $1 / 2$ if a harmonic function $f$ is convex, i. e., if $f(\mathbb{D})$ is a convex domain. Then Theorem 3 leads to

Corollary 1. Let $f=h+\bar{g}$ be a sense-preserving harmonic mapping of the unit disk $\mathbb{D}$ onto a convex domain, such that $a_{0}=a_{1}-1=b_{1}=0$. Then the domains $D_{r}=f\left(\mathbb{D}_{r}\right)$ are $R$-convex for every $r \leqslant r_{*}(R) \leqslant 2-\sqrt{3}$, where $r_{*}(R)$ is the smallest positive root of the equation

$$
\left(\frac{1-r}{1+r}\right)^{3} \frac{r^{2}-4 r+1}{r}=\frac{1}{R}
$$

Note that the radius $r_{*}(R)$ is not the best possible, because every convex harmonic function $f$ such that $a_{0}=a_{1}-1=b_{1}=0$ is convex in any disk $\mathbb{D}_{r}$ for $r \leqslant \sqrt{2}-1$ (cf., [5]) and $2-\sqrt{3}<\sqrt{2}-1$.
3. Coefficient bounds. In this section we introduce the families of normalized univalent harmonic functions onto $R$-convex domains and investigate their properties.

Let $f=h+\bar{g}$, where $h, g$ have form (2), and $f$ be sense-preserving. It is clear that the value $a_{0}=h(0)$ does not influence the radius of $R$-convexity of $f(\mathbb{D})$. Also, if $f$ is harmonic and the domain $f(\mathbb{D})$ is $R$-convex for some $R \in(0,+\infty)$, then $f(\mathbb{D}) / a_{1}$ is $\tilde{R}$-convex for $\tilde{R}=R /\left|a_{1}\right|$. Therefore let us assume that $a_{0}=a_{1}-1=0$.
Definition 2. Let $R \in(0,+\infty)$ be fixed and $C_{H, R}$ denote the set of all harmonic sense-preserving functions in the disk $\mathbb{D}$ such that $f(\mathbb{D})$ is $R$-convex and $a_{0}=a_{1}-1=0$. In addition, $C_{H, R}^{0}$ denotes the subset of $C_{H, R}$ that consists of all $f$ with $b_{1}=0$.

As has been mentioned above, the family of harmonic functions onto $R$-convex domains is wider than the family of harmonic convex functions of bounded type (satisfying inequality (4)). Proposition 1 claims that in the analytic case the family $C_{R}$ of normalized analytic convex function of bounded type consists of analytic mappings onto $R$-convex domains. So, $C_{R} \subset C_{H, R}^{0} \subset C_{H, R}$.

It is known [8] that $C_{R}$ is empty for $R<1$ and $C_{1}$ consists of one element $f \equiv z$ only. In the harmonic case, the same property also holds.
Proposition 2. The family $C_{H, R}$ is empty for any $R<1$. The only member of the family $C_{H, 1}$ is $f \equiv z$.
Proof. As we have mentioned above, every $R$-convex domain $D$ is an image of $\mathbb{D}$ under some analytic convex function of bounded type. It was proved [9] that $D$ is contained in some disk of radius $R$ in this case.

Therefore, if $f \in C_{H, R}$ then $f(\mathbb{D})$ is strictly convex subdomain of some disk of radius $R$. Then (cf., [5]) $f$ has a continuous boundary function $f\left(e^{i t}\right)=\rho(t) e^{i \theta(t)}$ on $\partial \mathbb{D}$ with continuous real $\rho(t), \theta(t), t \in[0,2 \pi)$; so, the generalisation of the Radó-Knezer-Choquet theorem claims that $f$ is the Poisson integral:

$$
f(z)=c+\frac{1}{2 \pi} \int_{0}^{2 \pi} \frac{1-|z|^{2}}{\left|e^{i t}-z\right|^{2}} \rho(t) e^{i \theta(t)} d t
$$

where $\rho(t) \leqslant R$ for all $t \in[0,2 \pi)$. It is easy to see that

$$
\left|a_{1}\right|=\left|f_{z}(0)\right|=\left|\frac{1}{2 \pi} \int_{0}^{2 \pi} \rho(t) e^{i(\theta(t)-t)} d t\right| \leqslant \frac{1}{2 \pi} \int_{0}^{2 \pi} \rho(t) d t .
$$

Therefore, $\left|a_{1}\right|<1$ if $\rho(t) \leqslant R<1$ and $C_{H, R}$ is empty in this case. If $R=1$, then the equality $\left|a_{1}\right|=1$ implies $\rho(t) \equiv 1$ on $[0,2 \pi)$. Therefore, $F(z)=f(z)-c$ maps the disk $\mathbb{D}$ exactly onto itself, if $a_{1}=1$. It is known [4] that the only harmonic automorphism of $\mathbb{D}$ with $a_{1}=1$ is $F \equiv z$. Thus $f \equiv z+c \equiv z$ because of $f(0)=0$.

The next theorem is an analogue of an area principle for harmonic mappings onto $R$-convex domains.
Theorem 4. Let $f=h+\bar{g} \in C_{H, R}$ where $h, g$ have form (2). Then

$$
\begin{equation*}
2 \sum_{k=1}^{\infty} k^{2}\left|a_{k}\right|^{2} \int_{0}^{1} \frac{r^{2 k-1}\left(1-r^{2}\right)}{\left(1+\left|b_{1}\right| r\right)^{2}} d r \leqslant \frac{R^{2}}{1-\left|b_{1}\right|^{2}} . \tag{6}
\end{equation*}
$$

Particularly, if $f \in C_{H, R}^{0}$ then

$$
\begin{equation*}
\frac{1}{2}+\sum_{k=2}^{\infty} \frac{k}{k+1}\left|a_{k}\right|^{2} \leqslant R^{2} \tag{7}
\end{equation*}
$$

Proof. As we have indicated above [9], every $R$-convex domain $D$ is contained in some disk of radius $R$. Therefore, area of $D=f(\mathbb{D})$ is not greater than $\pi R^{2}$ for any harmonic function $f \in C_{H, R}$. Jacobian of a harmonic function $f$ is equal to $\left|h^{\prime}\right|^{2}-\left|g^{\prime}\right|^{2}$. Also, the dilatation $\omega=g^{\prime} / h^{\prime}$ is analytic in $\mathbb{D}$ and meets the condition of the Schwarz lemma (cf., [7]). Therefore,

$$
\left|\frac{\omega(z)-\omega(0)}{1-\overline{\omega(0)} \omega(z)}\right| \leqslant|z| \text { and }|\omega(z)| \leqslant \frac{|z|+|\omega(0)|}{1+|\omega(0) z|}
$$

as a consequence. For $f \in C_{H, R}$, the coefficient $b_{1}=\omega(0)$ and the following estimations of area of $D$ are true:

$$
\begin{aligned}
& \pi R^{2} \geqslant \iint_{D} d u d v=\iint_{\mathbb{D}}\left(\left|h^{\prime}(z)\right|^{2}-\left|g^{\prime}(z)\right|^{2}\right) d x d y= \\
& =\iint_{\mathbb{D}}\left|h^{\prime}(z)\right|^{2}\left(1-|\omega(z)|^{2}\right) d x d y \geqslant \iint_{\mathbb{D}}\left|h^{\prime}(z)\right|^{2}\left(1-\left(\frac{|z|+\left|b_{1}\right|}{1+\left|b_{1} z\right|}\right)^{2}\right) d x d y= \\
& =\int_{0}^{2 \pi} \int_{0}^{1}\left|h^{\prime}\left(r e^{i t}\right)\right|^{2} \frac{\left(1-\left|b_{1}\right|^{2}\right)\left(1-r^{2}\right)}{\left(1+\left|b_{1}\right| r\right)^{2}} r d r d t= \\
& =\left(1-\left|b_{1}\right|^{2}\right) \int_{0}^{1} \frac{r\left(1-r^{2}\right)}{\left(1+\left|b_{1}\right| r\right)^{2}} \int_{0}^{2 \pi}\left|h^{\prime}\left(r e^{i t}\right)\right|^{2} d t d r
\end{aligned}
$$

For $h(z)=z+\sum_{k=2}^{\infty} a_{k} z^{k}$ the series

$$
\left|h^{\prime}\left(r e^{i t}\right)\right|^{2}=\left|\sum_{k=1}^{\infty} k a_{k} r^{k-1} e^{i(k-1) t}\right|^{2}=\sum_{k, l=1}^{\infty} k l a_{k} \overline{a_{l}} r^{k+l-2} e^{i(k-l) t}
$$

converges uniformly by $t$ for a fixed $r$ as a product of two uniformly converging series $\sum_{k=1}^{\infty} k a_{k} r^{k-1} e^{i(k-1) t}$ and $\sum_{l=1}^{\infty} l \overline{a_{l}} r^{l-1} e^{-i(l-1) t}$. The system of exponential functions $\left\{e^{i k t}\right\}$ is orthogonal on $[0,2 \pi]$. Then integration gives

$$
\int_{0}^{2 \pi}\left|h^{\prime}\left(r e^{i t}\right)\right|^{2} d t=\int_{0}^{2 \pi}\left|\sum_{k=1}^{\infty} k a_{k} r^{k-1} e^{i(k-1) t}\right|^{2} d t=2 \pi \sum_{k=1}^{\infty} k^{2}\left|a_{k}\right|^{2} r^{2 k-2}
$$

Continuing the lower estimation of the area, we obtain:

$$
\pi R^{2} \geqslant 2 \pi\left(1-\left|b_{1}\right|^{2}\right) \sum_{k=1}^{\infty} k^{2}\left|a_{k}\right|^{2} \int_{0}^{1} \frac{r^{2 k-1}\left(1-r^{2}\right)}{\left(1+\left|b_{1}\right| r\right)^{2}} d r
$$

and inequality (6) is proved. If a function $f \in C_{H, R}^{0}$, then $b_{1}=0$ and the second inequality (7) in Theorem 4 follows from (6).

The area theorem allows us to obtain coefficient estimations for harmonic mappings onto $R$-convex domains.

Corollary 1. If $f \in C_{H, R}^{0}$, then

$$
\left|a_{k}\right| \leqslant\left(\frac{k+1}{k}\left(R^{2}-\frac{1}{2}\right)\right)^{1 / 2} \quad \text { for } k \geqslant 2 .
$$

Indeed, the coefficient bounds for $a_{k}$ follow immediately from (7), because $1 / 2+k /(k+1)\left|a_{k}\right|^{2} \leqslant R^{2}$.

The coefficient problem is one of the most attractive and complicated in the theory of univalent harmonic mappings (cf., [5]). The sharp bound is still not proved even in the case of $\left|a_{2}\right|$ in the family $S_{H}^{0}$ of harmonic univalent mapping from $\mathbb{D}$ into $\mathbb{C}$ such that $a_{0}=a_{1}-1=b_{1}=0$. However, for some special subclasses of $S_{H}^{0}$ the sharp coefficient estimations are known. One of such subclasses was defined as the family $S_{H}^{0}(S)$ of all $f=h+\bar{g} \in S_{H}^{0}$ such that $F=h+e^{i \theta} g \in S$ for some constant $\theta \in \mathbb{R}$. Here $S$ denotes the famous class of univalent analytic functions $F$ in $\mathbb{D}$ such that $F(0)=F^{\prime}(0)-1=0$. Several years ago S . Ponnusamy and A. Sairam Kaliraj [15] obtained the sharp coefficient estimations in $S_{H}^{0}(S)$ and conjectured that $S_{H}^{0}(S)=S_{H}^{0}$. However, recently this conjecture was proved to be wrong [2]. Here we follow the same manner to obtain the coefficient bounds in the analogous subclass of $C_{H, R}^{0}$.
Definition 3. Let $C_{H, R}^{0}\left(C_{R}\right)$ denote the subclass of $C_{H, R}^{0}$ consisting of functions $f=h+\bar{g}$ such that $F=h+e^{i \theta} g \in C_{R}$ for some constant $\theta \in \mathbb{R}$.
K.-J. Wirths [19] obtained the sharp upper bounds for coefficients $A_{2}, A_{3}$ for functions $F(z)=z+A_{2} z^{2}+A_{3} z^{3}+\ldots$ in the families $C_{R}$ of analytic convex functions of bounded type:

$$
\begin{equation*}
\left|A_{2}\right| \leqslant \sqrt{1-\frac{1}{R}},\left|A_{3}\right| \leqslant 1-\frac{1}{R} \tag{8}
\end{equation*}
$$

Here we prove similar estimations in $C_{H, R}^{0}\left(C_{R}\right)$.
Theorem 5. Let $f=h+\bar{g} \in C_{H, R}^{0}\left(C_{R}\right)$. Then

$$
\begin{equation*}
\left|a_{2}\right| \leqslant \frac{1}{2}+\sqrt{1-\frac{1}{R}},\left|a_{3}\right| \leqslant \frac{4}{3}-\frac{1}{R}+\frac{2}{3} \sqrt{1-\frac{1}{R}} \tag{9}
\end{equation*}
$$

Both estimations are sharp when $R \rightarrow \infty$.

Proof. Analytic and co-analytic parts of harmonic function $f \in C_{H, R}^{0}$ satisfy the equality $g^{\prime}=\omega \cdot h^{\prime}$, where $\omega$ is the dilatation of $f$ and $|\omega|<1, \omega(0)=0$. Let $\omega(z)=\sum_{k=1}^{\infty} c_{k} z^{k}$ in $\mathbb{D}$. Then

$$
\sum_{k=2}^{\infty} k b_{k} z^{k-1}=\left(\sum_{k=1}^{\infty} c_{k} z^{k}\right) \cdot\left(\sum_{k=1}^{\infty} k a_{k} z^{k-1}\right)
$$

where $a_{1}=1$ and, hence, $b_{2}=c_{1} / 2, b_{3}=\left(c_{2}+2 c_{1} a_{2}\right) / 3$. Analytic function $\omega$ meets the conditions of the Schwarz lemma (cf., [7]). Therefore, $\left|c_{1}\right| \leqslant 1$ and $\left|c_{2}\right| \leqslant 1-\left|c_{1}\right|^{2}$ (see [1], for instance).

If $f=h+\bar{g} \in C_{H, R}^{0}\left(C_{R}\right)$, then, by definition, there exists some $\theta \in \mathbb{R}$ such that $F(z)=h(z)+e^{i \theta} g(z) \in C_{R}$. The second coefficient $A_{2}$ of an analytic convex function $F$ of bounded type has the form $A_{2}=a_{2}+e^{i \theta} b_{2}$. Then, using (8), we have

$$
\left|a_{2}\right| \leqslant\left|A_{2}\right|+\left|b_{2}\right| \leqslant\left|A_{2}\right|+\frac{\left|c_{1}\right|}{2} \leqslant \frac{1}{2}+\sqrt{1-\frac{1}{R}}
$$

To estimate the third coefficient, we note that $A_{3}=a_{3}+e^{i \theta} b_{3}$, where $b_{3}=\left(c_{2}+2 c_{1} a_{2}\right) / 3,\left|a_{2}\right| \leqslant\left|A_{2}\right|+\left|c_{1}\right| / 2$ and $\left|c_{2}\right| \leqslant 1-\left|c_{1}\right|^{2}$. Therefore, applying the second inequality (8), we conclude that

$$
\begin{aligned}
& \left|a_{3}\right| \leqslant\left|A_{3}\right|+\frac{1}{3}\left|c_{2}+2 c_{1} a_{2}\right| \leqslant\left|A_{3}\right|+\frac{1}{3}\left(1-\left|c_{1}\right|^{2}+\left|c_{1}\right|\left(2\left|A_{2}\right|+\left|c_{1}\right|\right)\right)= \\
& =\left|A_{3}\right|+\frac{1}{3}\left(1+2\left|c_{1}\right|\left|A_{2}\right|\right) \leqslant \frac{4}{3}-\frac{1}{R}+\frac{2}{3} \sqrt{1-\frac{1}{R}}
\end{aligned}
$$

If $R \rightarrow \infty$, then (9) becomes $\left|a_{2}\right| \leqslant 3 / 2$ and $\left|a_{3}\right| \leqslant 2$. This estimations coincide with the known sharp coefficient bounds for the convex harmonic mappings $f$ such that $a_{0}=a_{1}-1=b_{1}=0$. So, the sharpness of (9) for $R \rightarrow \infty$ is proved.

Note that inequalities (9) take the form $\left|a_{2}\right| \leqslant 1 / 2,\left|a_{3}\right| \leqslant 1 / 3$ when $R \rightarrow 1$. There are the best possible estimations [4] in the family of nonnormalised harmonic automorphisms of the unit disk $\mathbb{D}$.

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