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HYPERHOLOMORPHIC FUNCTIONS WITH VALUES IN A MODIFIED FORM OF QUATERNIONS

Abstract. We give the definition of hyperholomorphic pseudo-complex functions, i. e., functions with values in a special form of quaternions, and propose the necessary variables, functions, and Dirac operators to describe the Cauchy integral theorem and the generalized Cauchy-Riemann system. We investigate the properties and corollaries corresponding to the Cauchy integral theorem for the pseudo-complex number system discussed in this paper.

Key words: *hyperholomorphic, quaternion, dirac operator, Cauchy-Riemann system*

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1. Introduction. The non-commutative four-dimensional space \mathbb{R}^4 of hypercomplex numbers, which are called quaternions with four real numbers, was studied by Hamilton [5]. Since quaternions involve non-commutative multiplication, quaternions have different algebraic properties compared to the complex number system. In 1935, Fueter [2] defined regular quaternionic functions in \mathbb{R}^4 . Later Deavours [1] and Subdery [12] developed quaternionic analysis, based on complex analysis.

Many formulas in \mathbb{R}^4 are simpler and more convenient to apply in physics when written in terms of \mathbb{C}^2 . In [11], Nôno represented quaternions in the complex-number form. In [6], Kajiwara et al. gave an integrability condition for any hyperholomorphic function $f_1 + f_2j$ composed of harmonic complex-valued functions f_1 and f_2 in a pseudoconvex domain of \mathbb{C}^4 . In [7], [8], Kim et al. presented a ternary representation of real quaternions and also introduced the pseudo-complex number form with the modified basis \hat{i} . The regularity of a function defined in \mathbb{R}^3 relative to the commonly known properties of regular functions was defined.

Hamilton tried to generalize complex numbers to the form $a + ib + jc$, where $a, b, c \in \mathbb{R}$ and $i^2 = j^2 = -1$. However, since the set $\{a + ib + jc \mid a, b, c \in \mathbb{R}\}$ is not closed under multiplication (which was proved by Kenneth in 1966), this set cannot be generalized as an algebra. Later, Hamilton found a closed multiplication for complex numbers, denoted by $q = ix + jy + kz$, where $i^2 = j^2 = k^2 = ijk = -1$. Some interesting investigations were carried out on the set $\{a + ib + jc \mid a, b, c \in \mathbb{R}\}$. Leutwiler [9] studied the interplay between the solutions $f = u + iv + jw$ of the generalized Cauchy-Riemann system and functions of the reduced quaternionic variable $z = x + iy + jt$. Leutwiler showed that every solution f of that system defined in some neighborhood of the origin admits a series expansion in terms of the elementary polynomial solutions. In [3], [4], Gürlebeck and Sprößig studied quaternion-valued functions that are defined in open subsets of \mathbb{R}^n ($n = 3, 4$) and are solutions of generalized Cauchy-Riemann or Dirac systems. Their research is related to boundary-value problems and partial differential equations.

This paper recalls the properties resulting from the applications of the defined differential operators and the regularity of modified ternary functions. Using the properties of a modified ternary function, we present integration over the boundary of a domain in the modified ternary numbers. In addition, the present paper presents and verifies the Cauchy integral theorem for modified ternary functions. We also expose corollaries to the Cauchy integral theorem. The paper introduces the definitions of hyperholomorphic functions on the real ternary numbers and represents pseudo-complex numbers as a special form of quaternions, defined as $a + b\hat{i}$. In section 2, we provide the necessary variables, functions, and operators used in the paper. In section 3, we refer to Naser [10] and Nôno [11] in order to propose Dirac operators and Cauchy integral theorems. And then we introduce the properties and corollaries corresponding to the Cauchy integral theorem for the pseudo-complex number system.

2. Preliminaries. Let \mathbb{T} be the set of all ternary numbers:

$$\mathbb{T} = \{z \mid z = x_0 + x_1e_1 + x_2e_2, \quad x_0, x_1, x_2 \in \mathbb{R}\},$$

where $e_1^2 = e_2^2 = -1$ and $e_1e_2 = \sqrt{-1}$. An element z of \mathbb{T} can be written as

$$\begin{aligned} z &= x_0 + x_1e_1 + x_2e_2 = \\ &= x_0 + \frac{ae_1 + be_2}{\sqrt{a^2 + b^2}} \left(\frac{\sqrt{a^2 + b^2}}{ae_1 + be_2} x_1e_1 + \frac{\sqrt{a^2 + b^2}}{ae_1 + be_2} x_2e_2 \right) = \end{aligned}$$

$$= x_0 + \frac{ae_1 + be_2}{\sqrt{a^2 + b^2}} \left(\frac{ax_1 + bx_2}{\sqrt{a^2 + b^2}} + \frac{bx_1 - ax_2}{\sqrt{a^2 + b^2}} e_1 e_2 \right),$$

where a and b are real non-zero numbers. Let \hat{i} be the modified basis in \mathbb{T} , denoted by

$$\hat{i} = \frac{ae_1 + be_2}{\sqrt{a^2 + b^2}} \quad \text{and} \quad \hat{i}^2 = -1.$$

Then, an element z of \mathbb{T} can also be written as

$$z = x_0 + \hat{i}z_0;$$

such a number is called a pseudo-complex number; here

$$z_0 = \frac{ax_1 + bx_2}{\sqrt{a^2 + b^2}} + \frac{bx_1 - ax_2}{\sqrt{a^2 + b^2}} e_1 e_2.$$

The set of pseudo-complex numbers, denoted by \mathbb{P} , is isomorphic to $\mathbb{R} \times \mathbb{C}$; that is, $\mathbb{P} \cong \mathbb{R} \times \mathbb{C}$. The addition and multiplication for pseudo-complex numbers are given by

$$\begin{aligned} z \pm w &= (x_0 + \hat{i}z_0) \pm (y_0 + \hat{i}w_0) = \\ &= (x_0 \pm y_0) + \hat{i}(z_0 \pm w_0) \end{aligned}$$

and

$$\begin{aligned} zw &= (x_0 + \hat{i}z_0)(y_0 + \hat{i}w_0) = \\ &= (x_0y_0 - \bar{z}_0w_0) + \hat{i}(x_0w_0 + z_0y_0), \end{aligned}$$

respectively. From the multiplication over \mathbb{P} , we can obtain $z_0\hat{i} = \hat{i}\bar{z}_0$. Hence, the multiplication over \mathbb{P} is closed and associative but not commutative.

Let \bar{z} be the conjugate of z , denoted by $\bar{z} = x_0 - \hat{i}z_0$ with $z\bar{z} = \bar{z}z$. Also, the norm $|\cdot|$ is written by

$$|z| := \sqrt{z\bar{z}} = \sqrt{x_0^2 + \bar{z}_0z_0} = \sqrt{x_0^2 + x_1^2 + x_2^2}.$$

The inverse element z^{-1} of \mathbb{P} is denoted by

$$z^{-1} = \frac{\bar{z}}{|z|^2}.$$

Now, consider the definition of hyperholomorphy for pseudo-complex functions. First, the differential operators are given by

$$D = \frac{\partial}{\partial x_0} - \hat{i} \frac{\partial}{\partial \bar{z}_0} = \frac{\partial}{\partial x_0} - e_1 \frac{\partial}{\partial x_1} - e_2 \frac{\partial}{\partial x_2}$$

and

$$\bar{D} = \frac{\partial}{\partial x_0} + \hat{i} \frac{\partial}{\partial \bar{z}_0} = \frac{\partial}{\partial x_0} + e_1 \frac{\partial}{\partial x_1} + e_2 \frac{\partial}{\partial x_2},$$

where

$$\begin{aligned} \frac{\partial}{\partial z_0} &= \frac{1}{2} \frac{\partial}{\partial x_1} \left(\frac{a}{\sqrt{a^2 + b^2}} - \frac{b}{\sqrt{a^2 + b^2}} e_1 e_2 \right) + \\ &\quad + \frac{\partial}{\partial x_2} \left(\frac{b}{\sqrt{a^2 + b^2}} + \frac{a}{\sqrt{a^2 + b^2}} e_1 e_2 \right) = \\ &= \frac{1}{2} \left(\frac{a}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_1} + \frac{b}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_2} \right) - \\ &\quad - \left(\frac{b}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_1} - \frac{a}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_2} \right) e_1 e_2 \end{aligned}$$

and

$$\begin{aligned} \frac{\partial}{\partial \bar{z}_0} &= \frac{1}{2} \frac{\partial}{\partial x_1} \left(\frac{a}{\sqrt{a^2 + b^2}} + \frac{b}{\sqrt{a^2 + b^2}} e_1 e_2 \right) + \\ &\quad + \frac{\partial}{\partial x_2} \left(\frac{b}{\sqrt{a^2 + b^2}} - \frac{a}{\sqrt{a^2 + b^2}} e_1 e_2 \right) = \\ &= \frac{1}{2} \left(\frac{a}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_1} + \frac{b}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_2} \right) + \\ &\quad + \left(\frac{b}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_1} - \frac{a}{\sqrt{a^2 + b^2}} \frac{\partial}{\partial x_2} \right) e_1 e_2. \end{aligned}$$

Then, the Laplacian operator is given by

$$\begin{aligned} \Delta &:= D\bar{D} = \bar{D}D = \left(\frac{\partial}{\partial x_0} - \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) \left(\frac{\partial}{\partial x_0} + \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) = \\ &= \frac{\partial^2}{\partial x_0^2} + \frac{\partial^2}{\partial z_0 \partial \bar{z}_0} = \frac{\partial^2}{\partial x_0^2} + \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}. \end{aligned}$$

3. Properties of hyperholomorphic functions. Let Ω be a domain in \mathbb{R}^3 . Consider a function f defined on Ω and with values in \mathbb{P} such that $f : \Omega \rightarrow \mathbb{P}$ is defined by

$$f = u_0 + u_1 e_1 + u_2 e_2 = u_0 + \hat{i} f_0.$$

That is, f satisfies

$$z = (x_0, x_1, x_2) \in \Omega \mapsto f(z) = u_0(x_0, x_1, x_2) + \hat{i} f_0(x_0, x_1, x_2) \in \mathbb{P},$$

where u_r ($r = 0, 1, 2$) are real-valued functions and

$$f_0 = \frac{au_1 + bu_2}{\sqrt{a^2 + b^2}} + \frac{bu_1 - au_2}{\sqrt{a^2 + b^2}} e_1 e_2$$

is a complex-valued function. The function f is called a pseudo-complex function. Let the differential operators defined in Section 2 be applied to a function $f : \Omega \rightarrow \mathbb{P}$. Then we have the following equalities:

$$Df = \left(\frac{\partial}{\partial x_0} - \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) (u_0 + \hat{i} f_0) = \left(\frac{\partial u_0}{\partial x_0} + \frac{\partial f_0}{\partial z_0} \right) + \hat{i} \left(\frac{\partial f_0}{\partial x_0} - \frac{\partial u_0}{\partial \bar{z}_0} \right)$$

and

$$\bar{D}f = \left(\frac{\partial}{\partial x_0} + \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) (u_0 + \hat{i} f_0) = \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial f_0}{\partial z_0} \right) + \hat{i} \left(\frac{\partial f_0}{\partial x_0} + \frac{\partial u_0}{\partial \bar{z}_0} \right).$$

Since the set \mathbb{P} has non-commutative multiplication, we also apply operators to the function f from the right. We have

$$fD = (u_0 + \hat{i} f_0) \left(\frac{\partial}{\partial x_0} - \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) = \left(\frac{\partial u_0}{\partial x_0} + \frac{\partial \bar{f}_0}{\partial \bar{z}_0} \right) + \hat{i} \left(\frac{\partial f_0}{\partial x_0} - \frac{\partial u_0}{\partial \bar{z}_0} \right)$$

and

$$f\bar{D} = (u_0 + \hat{i} f_0) \left(\frac{\partial}{\partial x_0} + \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) = \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial \bar{f}_0}{\partial \bar{z}_0} \right) + \hat{i} \left(\frac{\partial f_0}{\partial x_0} + \frac{\partial u_0}{\partial \bar{z}_0} \right).$$

Hence, the equality $\bar{D}f = 0$ implies that f satisfies the following equations:

$$\frac{\partial u_0}{\partial x_0} = \frac{\partial f_0}{\partial z_0} \quad \text{and} \quad \frac{\partial f_0}{\partial x_0} = -\frac{\partial u_0}{\partial \bar{z}_0}, \quad (1)$$

called the (left-)pseudo-complex Cauchy-Riemann equations. Similarly, if f satisfies $f\bar{D} = 0$ then we obtain the equations:

$$\frac{\partial u_0}{\partial x_0} = \frac{\partial \bar{f}_0}{\partial \bar{z}_0} \quad \text{and} \quad \frac{\partial f_0}{\partial x_0} = -\frac{\partial u_0}{\partial \bar{z}_0}, \quad (2)$$

called the (right-)pseudo-complex Cauchy-Riemann equations. Basing on the definition of the Laplacian, we also obtain

$$\begin{aligned} \Delta f &= (D\bar{D})f = \left(\frac{\partial^2}{\partial x_0^2} + \frac{\partial^2}{\partial z_0 \partial \bar{z}_0} \right) (u_0 + \hat{i}f_0) = \\ &= \left(\frac{\partial^2 u_0}{\partial x_0^2} + \frac{\partial^2 u_0}{\partial z_0 \partial \bar{z}_0} \right) + \hat{i} \left(\frac{\partial^2 f_0}{\partial x_0^2} + \frac{\partial^2 f_0}{\partial \bar{z}_0 \partial z_0} \right). \end{aligned}$$

Since multiplication over \mathbb{P} is associative,

$$(D\bar{D})f = D(\bar{D}f)$$

Therefore,

$$\begin{aligned} D(\bar{D}f) &= \left(\frac{\partial}{\partial x_0} - \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) \left\{ \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial f_0}{\partial z_0} \right) + \hat{i} \left(\frac{\partial f_0}{\partial x_0} + \frac{\partial u_0}{\partial \bar{z}_0} \right) \right\} = \\ &= \frac{\partial^2 u_0}{\partial x_0^2} - \frac{\partial^2 f_0}{\partial x_0 \partial z_0} + \hat{i} \left(\frac{\partial^2 f_0}{\partial x_0^2} + \frac{\partial^2 u_0}{\partial x_0 \partial \bar{z}_0} \right) - \\ &\quad - \hat{i} \left(\frac{\partial^2 u_0}{\partial \bar{z}_0 \partial x_0} - \frac{\partial^2 f_0}{\partial \bar{z}_0 \partial z_0} \right) + \left(\frac{\partial^2 f_0}{\partial z_0 \partial x_0} + \frac{\partial^2 u_0}{\partial z_0 \partial \bar{z}_0} \right) = \\ &= \left(\frac{\partial^2 u_0}{\partial x_0^2} + \frac{\partial^2 u_0}{\partial z_0 \partial \bar{z}_0} \right) + \hat{i} \left(\frac{\partial^2 f_0}{\partial x_0^2} + \frac{\partial^2 f_0}{\partial \bar{z}_0 \partial z_0} \right). \end{aligned}$$

Definition 1. Let Ω be an open set in \mathbb{R}^3 . A function $f : \Omega \rightarrow \mathbb{P}$,

$$f(z) = u_0(x_0, x_1, x_2) + \hat{i}f_0(x_0, x_1, x_2),$$

is said to be left-hyperholomorphic on Ω if f satisfies the following two conditions:

- 1) u_0 is a real-analytic function and f_0 is a holomorphic function,
- 2) f satisfies the equation $\bar{D}f = 0$ on Ω .

Involving the non-commutativity of multiplication, comparing (1) and (2), we also give the following

Definition 2. Let Ω be an open set in \mathbb{R}^3 . A function $f : \Omega \rightarrow \mathbb{P}$,

$$f(z) = u_0(x_0, x_1, x_2) + \hat{i}f_0(x_0, x_1, x_2)$$

is said to be right hyperholomorphic on Ω if f satisfies the following two conditions:

- 1) u_0 is a real-analytic function and f_0 is a holomorphic function.
- 2) f satisfies the equation $f\bar{D} = 0$ on Ω ,

Since a right hyperholomorphic function is dealt with in a similar manner as a left hyperholomorphic function, we only consider left hyperholomorphic functions and simply call them hyperholomorphic.

Proposition 1. Let Ω be an open set in \mathbb{R}^3 and f be a hyperholomorphic function on Ω . Then

$$Df = f' = \frac{\partial f}{\partial x_0} = -\hat{i}\frac{\partial f}{\partial \bar{z}_0}.$$

Proof. Since f is a hyperholomorphic function on Ω , (1) yields

$$Df = \left(\frac{\partial u_0}{\partial x_0} + \frac{\partial f_0}{\partial z_0} \right) + \hat{i} \left(\frac{\partial f_0}{\partial x_0} - \frac{\partial u_0}{\partial \bar{z}_0} \right) = \frac{\partial u_0}{\partial x_0} + \hat{i}\frac{\partial f_0}{\partial x_0} = \frac{\partial}{\partial x_0}f.$$

Moreover, by (1), for Df we also have

$$Df = \frac{\partial f_0}{\partial z_0} - \hat{i}\frac{\partial u_0}{\partial \bar{z}_0} = -\hat{i}^2\frac{\partial f_0}{\partial z_0} - \hat{i}\frac{\partial u_0}{\partial \bar{z}_0} = -\hat{i} \left(\frac{\partial}{\partial \bar{z}_0}\hat{i}f_0 + \frac{\partial}{\partial \bar{z}_0}u_0 \right) = -\hat{i}\frac{\partial}{\partial \bar{z}_0}f.$$

□

Let us now consider the properties of hyperholomorphic functions in pseudo-complex numbers.

Proposition 2. Let Ω be an open set in \mathbb{R}^3 and f and g be hyperholomorphic functions on Ω . Then

- 1) αf is hyperholomorphic on Ω if α is any real constant,
- 2) $f\alpha$ is hyperholomorphic on Ω if α is any ternary constant,
- 3) $f \pm g$ is hyperholomorphic on Ω .

Proof. The condition that f and g are both hyperholomorphic functions means that they satisfy (1). For proving items 1) – 3), it suffices to satisfy the second condition of Definition 1.

- 1) When α is any real constant, it is obvious that $\overline{D}(\alpha f) = 0$.
- 2) Let α be a pseudo-complex constant, $\alpha = a_0 + \hat{i}\alpha_0$, where a_0 is real and

$$\alpha = \frac{c_1 a_1 + c_2 a_2}{\sqrt{c_1^2 + c_2^2}} + \frac{c_2 a_1 - c_1 a_2}{\sqrt{c_1^2 + c_2^2}} e_1 e_2$$

with c_r and a_r ($r = 1, 2$) being real numbers. By (1), we infer

$$\begin{aligned} \overline{D}(f\alpha) &= \left(\frac{\partial}{\partial x_0} + \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) \{ (u_0 a_0 - \bar{f}_0 \alpha_0) + \hat{i} (u_0 \alpha_0 + f_0 a_0) \} = \\ &= \left(\frac{\partial u_0}{\partial x_0} a_0 - \frac{\partial \bar{f}_0}{\partial x_0} \alpha_0 - \frac{\partial u_0}{\partial z_0} \alpha_0 - \frac{\partial f_0}{\partial z_0} a_0 \right) + \\ &\quad + \hat{i} \left(\frac{\partial u_0}{\partial x_0} \alpha_0 + \frac{\partial f_0}{\partial x_0} a_0 + \frac{\partial u_0}{\partial \bar{z}_0} a_0 - \frac{\partial \bar{f}_0}{\partial \bar{z}_0} \alpha_0 \right) = 0. \end{aligned}$$

- 3) Since f and g are hyperholomorphic functions on Ω , we have

$$\begin{aligned} \overline{D}(f \pm g) &= \left(\frac{\partial}{\partial x_0} + \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) \{ (u_0 \pm v_0) + \hat{i} (f_0 \pm g_0) \} = \\ &= \left(\frac{\partial u_0}{\partial x_0} \pm \frac{\partial v_0}{\partial x_0} - \frac{\partial f_0}{\partial z_0} \mp \frac{\partial g_0}{\partial z_0} \right) + \\ &\quad + \hat{i} \left(\frac{\partial u_0}{\partial \bar{z}_0} \pm \frac{\partial v_0}{\partial \bar{z}_0} + \frac{\partial f_0}{\partial x_0} a_0 \pm \frac{\partial g_0}{\partial x_0} \right) = 0. \end{aligned}$$

□

Example. Let Ω be an open set in \mathbb{R}^3 and f and g be hyperholomorphic functions on Ω . Then fg is not always hyperholomorphic on Ω . Since f and g are hyperholomorphic functions on Ω , we obtain

$$\begin{aligned} \overline{D}(fg) &= \left(\frac{\partial}{\partial x_0} + \hat{i} \frac{\partial}{\partial \bar{z}_0} \right) \{ (u_0 v_0 - \bar{f}_0 g_0) + \hat{i} (u_0 g_0 + f_0 v_0) \} = \\ &= \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial f_0}{\partial z_0} \right) v_0 + u_0 \left(\frac{\partial v_0}{\partial x_0} - \frac{\partial g_0}{\partial z_0} \right) - \\ &\quad - \left(\frac{\partial \bar{f}_0}{\partial x_0} + \frac{\partial u_0}{\partial z_0} \right) g_0 - \left(\bar{f}_0 \frac{\partial g_0}{\partial x_0} + f_0 \frac{\partial v_0}{\partial z_0} \right) + \\ &\quad + \hat{i} \left\{ \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial \bar{f}_0}{\partial \bar{z}_0} \right) g_0 + u_0 \left(\frac{\partial g_0}{\partial x_0} + \frac{\partial v_0}{\partial \bar{z}_0} \right) \right\} + \end{aligned}$$

$$\begin{aligned}
& + \hat{i} \left\{ \left(\frac{\partial f_0}{\partial x_0} + \frac{\partial u_0}{\partial \bar{z}_0} \right) v_0 + \left(f_0 \frac{\partial v_0}{\partial x_0} - \bar{f}_0 \frac{\partial g_0}{\partial \bar{z}_0} \right) \right\} = \\
& = -\bar{f}_0 \frac{\partial g_0}{\partial x_0} - f_0 \frac{\partial v_0}{\partial z_0} + \hat{i} f_0 \frac{\partial v_0}{\partial x_0} - \hat{i} \bar{f}_0 \frac{\partial g_0}{\partial \bar{z}_0} = \\
& = \bar{f}_0 \frac{\partial v_0}{\partial \bar{z}_0} - f_0 \frac{\partial v_0}{\partial z_0} + \hat{i} f_0 \frac{\partial g_0}{\partial z_0} - \hat{i} \bar{f}_0 \frac{\partial g_0}{\partial \bar{z}_0} = \bar{f}_0 \frac{\partial g}{\partial \bar{z}_0} - f_0 \frac{\partial g}{\partial z_0}.
\end{aligned}$$

If $\bar{f}_0 \frac{\partial g}{\partial \bar{z}_0} - f_0 \frac{\partial g}{\partial z_0} = 0$ then the function fg is hyperholomorphic on Ω . For example, if f is a real-valued function then fg is hyperholomorphic on Ω . However, when $\bar{f}_0 \frac{\partial g}{\partial \bar{z}_0} \neq f_0 \frac{\partial g}{\partial z_0}$, fg is not hyperholomorphic on Ω .

Put

$$\omega = dz_0 \wedge d\bar{z}_0 - \hat{i} dx_0 \wedge dz_0.$$

Theorem 1. Let Ω be a domain in \mathbb{R}^3 and U be any domain in Ω with smooth boundary bU such that $\bar{U} \subset \Omega$. If f is a hyperholomorphic on Ω then

$$\int_{bU} \omega f = 0.$$

Proof. We have

$$\begin{aligned}
\omega f &= (dz_0 \wedge d\bar{z}_0 - \hat{i} dx_0 \wedge dz_0)(u_0 + \hat{i} f_0) = \\
&= (u_0 dz_0 \wedge d\bar{z}_0 + f_0 dx_0 \wedge d\bar{z}_0) + \hat{i} (f_0 d\bar{z}_0 \wedge dz_0 - u_0 dx_0 \wedge dz_0).
\end{aligned}$$

Let ∂ and $\bar{\partial}$ be the following operators:

$$\partial = \frac{1}{2} \frac{\partial}{\partial x_0} dx_0 + \frac{\partial}{\partial z_0} dz_0 \quad \text{and} \quad \bar{\partial} = \frac{1}{2} \frac{\partial}{\partial x_0} dx_0 + \frac{\partial}{\partial \bar{z}_0} d\bar{z}_0.$$

Then

$$\begin{aligned}
d(\omega f) &= (\partial + \bar{\partial})(\omega f) = \left(\frac{\partial}{\partial x_0} dx_0 + \frac{\partial}{\partial z_0} dz_0 + \frac{\partial}{\partial \bar{z}_0} d\bar{z}_0 \right) (\omega f) = \\
&= \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial f_0}{\partial z_0} \right) dx_0 \wedge dz_0 \wedge d\bar{z}_0 + \hat{i} \left(\frac{\partial f_0}{\partial x_0} + \frac{\partial u_0}{\partial \bar{z}_0} \right) dx_0 \wedge dz_0 \wedge d\bar{z}_0 = 0
\end{aligned}$$

in U . It now suffices to apply the Stokes theorem. \square

Theorem 2. Let Ω be an open set in \mathbb{R}^3 . If f is hyperholomorphic on Ω then u_0 and f_0 are harmonic functions on Ω . Moreover, f is harmonic on Ω .

Proof. It suffices to show that $\Delta u_0 = 0$ and $\Delta f_0 = 0$. Indeed, we have

$$\begin{aligned}\Delta u_0 &= (D\bar{D})u_0 = \frac{\partial^2 u_0}{\partial x_0^2} + \frac{\partial^2 u_0}{\partial z_0 \partial \bar{z}_0} = \frac{\partial}{\partial x_0} \frac{\partial f_0}{\partial z_0} - \frac{\partial}{\partial z_0} \frac{\partial f_0}{\partial x_0} = 0, \\ \Delta f_0 &= (D\bar{D})f_0 = \frac{\partial^2 f_0}{\partial x_0^2} + \frac{\partial^2 f_0}{\partial z_0 \partial \bar{z}_0} = -\frac{\partial}{\partial x_0} \frac{\partial u_0}{\partial \bar{z}_0} + \frac{\partial}{\partial \bar{z}_0} \frac{\partial u_0}{\partial x_0} = 0.\end{aligned}$$

By these equalities and (1), we can obtain the equality $\Delta f = 0$ as follows:

$$\begin{aligned}\Delta f &= (D\bar{D})f = \left(\frac{\partial^2 u_0}{\partial x_0^2} - \frac{\partial^2 f_0}{\partial x_0 \partial z_0} + \frac{\partial^2 f_0}{\partial z_0 \partial x_0} + \frac{\partial^2 u_0}{\partial z_0 \partial \bar{z}_0} \right) + \\ &\quad + \hat{i} \left(\frac{\partial^2 f_0}{\partial x_0^2} + \frac{\partial^2 u_0}{\partial x_0 \partial \bar{z}_0} - \frac{\partial^2 u_0}{\partial \bar{z}_0 \partial x_0} + \frac{\partial^2 f_0}{\partial \bar{z}_0 \partial z_0} \right) = \\ &= \frac{\partial}{\partial x_0} \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial f_0}{\partial z_0} \right) + \frac{\partial}{\partial z_0} \left(\frac{\partial f_0}{\partial x_0} + \frac{\partial u_0}{\partial \bar{z}_0} \right) + \\ &\quad + \hat{i} \frac{\partial}{\partial x_0} \left(\frac{\partial f_0}{\partial x_0} + \frac{\partial u_0}{\partial \bar{z}_0} \right) + \hat{i} \frac{\partial}{\partial \bar{z}_0} \left(-\frac{\partial u_0}{\partial x_0} + \frac{\partial f_0}{\partial z_0} \right) = 0.\end{aligned}$$

Thus, f is a harmonic function on Ω . \square

Consider the following example related to the statement presented in Theorem 2.

Example. Let u_0 be a real-valued harmonic function such that

$$u_0(z) = \frac{x_0}{|z|^4}$$

in a domain $D \subset \mathbb{P}$. Then the hyper-conjugate harmonic function f_0 of u_0 can be found in D as

$$f_0 = -\frac{z_0}{|z|^4}.$$

Moreover, $u_0 + \hat{i}f_0$ is hyperholomorphic in D .

The following theorem is the Cauchy integral formula for a hyperholomorphic function in \mathbb{P} .

Theorem 3. *Let Ω be a bounded domain in \mathbb{P} and $f = u_0 + \hat{i}f_0$ be hyperholomorphic on $\bar{\Omega}$. Then, for every $z = x_0 + \hat{i}z_0 \in \Omega$, f can be*

expressed as

$$f(z) = \frac{1}{2\pi^2} \int_{\Omega} -\frac{(\bar{\zeta} - \bar{z})}{|\zeta - z|^4} d\omega_{\zeta} f(\zeta) - \frac{1}{2\pi^2} \int_{b\Omega} -\frac{(\bar{\zeta} - \bar{z})}{|\zeta - z|^4} d\omega_{\zeta} f(\zeta),$$

where $\zeta = y_0 + \hat{i}\zeta_0$ and $\omega_{\zeta} = d\zeta_0 \wedge d\bar{\zeta}_0 - \hat{i}dy_0 \wedge d\zeta_0$.

Proof. In order to conveniently find the formula of Theorem 3, we put $\phi(\zeta, z) = (\bar{\zeta} - \bar{z})$ and $\psi(\zeta, z) = |\zeta - z|^4$. Let R be the distance between $b\Omega$ and z . Let $B = B(z, \rho)$ be the open ball of radius ρ with center $z \in \Omega$, where $0 < \rho < R$. Suppose $\Omega(z, \rho) = \Omega - B$. Since $\frac{\phi(\zeta, z)}{\psi(\zeta, z)}$ is hyperholomorphic, by the Stokes theorem, we infer

$$\begin{aligned} \int_{\Omega(z, \rho)} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} d\omega_{\zeta} f(\zeta) &= \int_{\Omega(z, \rho)} d \left\{ -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta) \right\} = \\ &= \int_{b\Omega(z, \rho)} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta) = \\ &= \int_{b\Omega} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta) - \int_{bB} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta). \end{aligned}$$

Moreover, we obtain

$$\begin{aligned} \int_{bB} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta) &= \int_B d \left(-\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta) \right) = \\ &= \int_B d \left\{ -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \right\} \omega_{\zeta} f(\zeta) + \int_B \left\{ -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \right\} d\omega_{\zeta} f(\zeta) = \\ &= \frac{1}{\rho^4} \left\{ \int_B f(\zeta) dx_0 \wedge dz_0 \wedge d\bar{z}_0 - \int_B \phi(\zeta, z) d\omega_{\zeta} f(\zeta) \right\}. \end{aligned}$$

Since f is hyperholomorphic in $\bar{\Omega}$, we have

$$\begin{aligned} \lim_{\rho \rightarrow 0} \frac{1}{\rho^4} \int_B f(\zeta) dx_0 \wedge dz_0 \wedge d\bar{z}_0 &= -2\pi^2 f(z), \\ \lim_{\rho \rightarrow 0} \frac{1}{\rho^4} \int_B \phi(\zeta, z) d\omega_{\zeta} f(\zeta) &= 0. \end{aligned}$$

Hence,

$$\int_{\Omega} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} d\omega_{\zeta} f(\zeta) = \int_{b\Omega} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta) + 2\pi^2 f(z).$$

Thus, the function $f(z)$ can be expressed as

$$f(z) = \frac{1}{2\pi^2} \int_{\Omega} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} d\omega_{\zeta} f(\zeta) - \frac{1}{2\pi^2} \int_{b\Omega} -\frac{\phi(\zeta, z)}{\psi(\zeta, z)} \omega_{\zeta} f(\zeta).$$

□

Corollary 1. Let Ω be a bounded domain in \mathbb{T} and $f = u_0 + \hat{i}f_0$ be hyperholomorphic in a bounded domain $\Omega \subset \mathbb{T}$. Then, for every $z \in \Omega$, the function f can be expressed as

$$\begin{aligned} f(z) &= \frac{1}{2\pi^2} \int_{b\Omega} \frac{(\bar{\zeta} - \bar{z})}{|\zeta - z|^4} \omega_{\zeta} f(\zeta) = \\ &= \frac{1}{2\pi^2} \int_{b\Omega} \frac{(y_0 - x_0) - \hat{i}(\zeta_0 - z_0)}{(|y_0 - x_0|^2 + |\zeta_0 - z_0|^2)^2} \omega_{\zeta} f(\zeta). \end{aligned}$$

Proof. Since f is a hyperholomorphic function on Ω , we have

$$d\omega_{\zeta} f(\zeta) = 0$$

and the corollary follows by Theorem 3. □

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